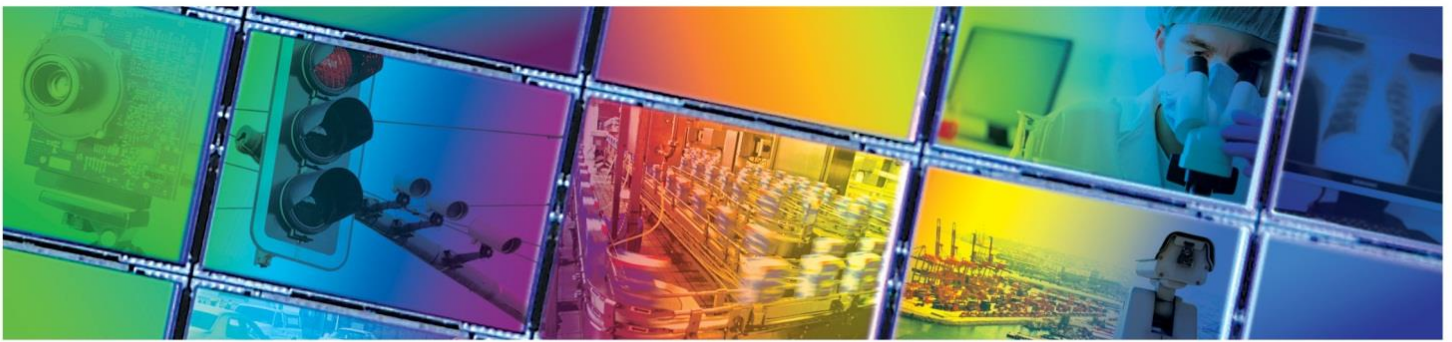


ON Semiconductor®



KAF-18500 IMAGE SENSOR
5270 (H) X 3516 (V) FULL FRAME CCD IMAGE SENSOR



JUNE 24, 2014
DEVICE PERFORMANCE SPECIFICATION
REVISION 1.1 PS-0074



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Summary Specification

KAF-18500 Image Sensor

DESCRIPTION

The KAF-18500 is a dual output, high performance color CCD (charge coupled device) image sensor with 5270 (H) x 3516 (V) photoactive pixels designed for a wide range of color image sensing applications including digital imaging. Each pixel contains anti-blooming protection by means of a lateral overflow drain thereby preventing image corruption during high light level conditions. Each of the 6.8 μm square pixels are selectively covered with red, green or blue pigmented filters for color separation. Microlenses are added for improved sensitivity.

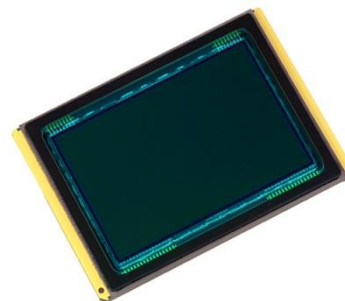
The sensor utilizes the TRUESENSE Transparent Gate Electrode to improve sensitivity compared to the use of a standard front side illuminated polysilicon electrode.

FEATURES

- TRUESENSE Transparent Gate Electrode for high sensitivity
- High resolution, 35 mm format
- Broad dynamic range
- Low noise
- Large image area

APPLICATIONS

- Digital Still Cameras



| Parameter | Typical Value |
|--|---|
| Architecture | Full Frame CCD; with Square Pixels |
| Total Number of Pixels | 5422 (H) x 3610 (V) = 19.6 M |
| Number of Effective Pixels | 5310 (H) x 3556 (V) = 18.8 M |
| Number of Active Pixels | 5270 (H) x 3516 (V) = 18.5 M |
| Pixel Size | 6.8 μm (H) x 6.8 μm (V) |
| Imager Size | 43.1 mm (diagonal) |
| Chip Size | 37.8 mm (H) x 26.4 mm (V) |
| Aspect Ratio | 3:2 |
| Saturation Signal | 42 ke^- |
| Charge to Voltage Conversion | 25 $\mu\text{V}/\text{e}^-$ |
| Quantum Efficiency (RGB) | 30%, 45%, 40% |
| Read Noise (f = 24 MHz) | 15.7 e^- |
| Dark Signal (T = 60 °C) | 50 pA/cm^2 |
| Dark Current Doubling Temperature | 5.3 °C |
| Linear Dynamic Range (f = 24 MHz, T = 60 °C) | 68.1 dB |
| Charge Transfer Efficiency (HCTE/VCTE) | 0.999995 0.999998 |
| Blooming Protection (4 ms exposure time) | 5600X saturation exposure |
| Maximum Data Rate | 24 MHz |
| Readout Mode | Dual output only |
| Package | PGA |
| Cover Glass | AR coated (S8612) |

Unless noted, all parameters above are specified at T = 20 °C to 25 °C



Ordering Information

| Catalog Number | Product Name | Description | Marking Code |
|----------------|------------------------|--|------------------|
| 4H2058 | KAF-18500-NXA-JH-AA-08 | Special Color, Aperture, Enhanced, ESD, LOD, Microlens, Sealed IR Cover Glass , 0.8 mm glass | KAF-18500-NXA-08 |
| 4H2059 | KAF-18500-NXA-JH-AE-08 | Special Color, Aperture, Enhanced, ESD, LOD, Microlens, Sealed IR Cover Glass , 0.8 mm glass [Engineering Grade] | KAF-18500-NXA-08 |

See Application Note *Product Naming Convention* for a full description of the naming convention used for image sensors. For reference documentation, including information on evaluation kits, please visit our web site at www.truesenseimaging.com.

Please address all inquiries and purchase orders to:

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1964 Lake Avenue
Rochester, New York 14615

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E-mail: info@truesenseimaging.com

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Device Description

ARCHITECTURE

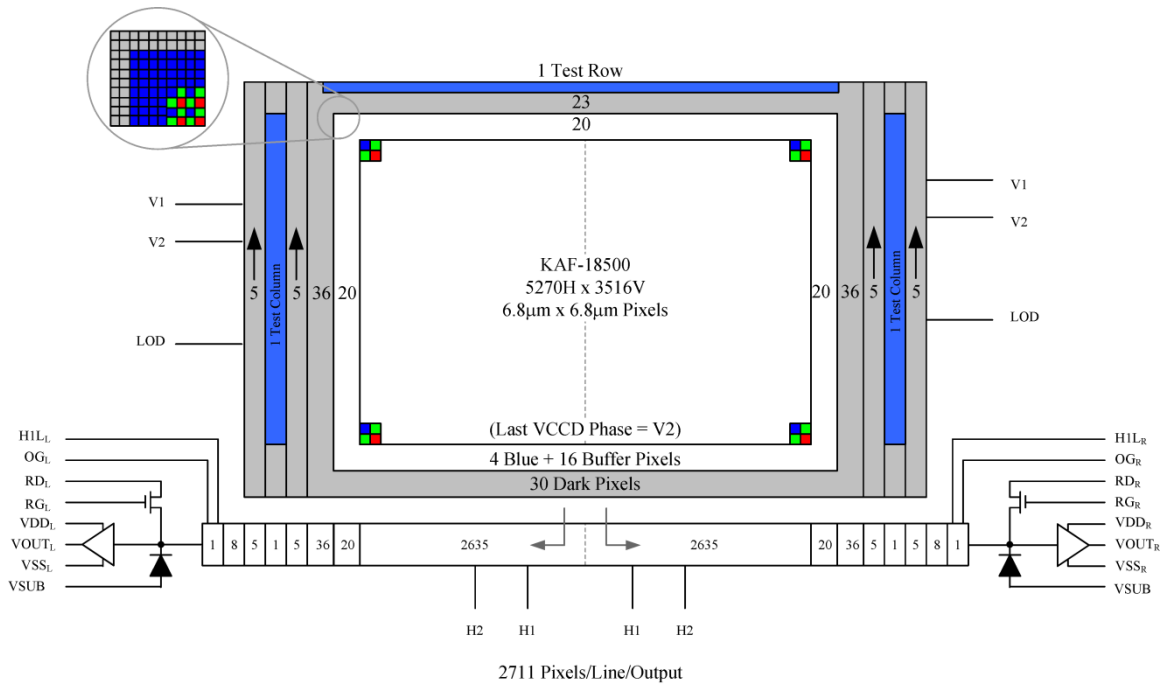


Figure 1: Block Diagram



Dark Reference Pixels

Surrounding the periphery of the device is a border of light shielded pixels creating a dark region. Within this dark region, exist light shielded pixels that include 36 leading dark pixels on every line. There are also 30 full dark lines at the start and 23 full dark lines at the end of every frame. Under normal circumstances, these pixels do not respond to light and may be used as a dark reference.

Dummy Pixels

Within each horizontal shift register there are 20 leading additional shift phases required before the dark reference pixels: (1 + 8 + 5 + 1 + 5) (See Figure 1). These pixels are designated as dummy pixels and should not be used to determine a dark reference level.

Active Buffer Pixels

Forming the outer boundary of the effective active pixel region, there are 20 unshielded active buffer pixels between the photoactive area and the dark reference. These pixels are light sensitive but they are not tested for defects and non-uniformities. For the leading 20 active column pixels, the first 4 pixels are covered with blue pigment while the remaining are arranged in a Bayer pattern (R, GR, GB, B).

IMAGE ACQUISITION

An electronic representation of an image is formed when incident photons falling on the sensor plane create electron-hole pairs within the device. These photon-induced electrons are collected locally by the formation of potential wells at each photogate or pixel site. The number of electrons collected is linearly dependent on light level and exposure time and non-linearly dependent on wavelength. When the pixel's capacity is reached, excess electrons are discharged into the lateral overflow drain to prevent crosstalk or 'blooming'. During the integration period, the V1 and V2 register clocks are held at a constant (low) level.

CHARGE TRANSPORT

The integrated charge from each photogate (pixel) is transported to the output using a two-step process. Each line (row) of charge is first transported from the vertical CCD's to a horizontal CCD register using the V1 and V2 register clocks. The horizontal CCD is presented with a new line on the falling edge of V2 while H1 is held high. The horizontal CCD's then transport each line, pixel by pixel, to the output structure by alternately clocking the H1 and H2 pins in a complementary fashion. A separate connection to the last H1 phase (H1L) is provided to improve the transfer speed of charge to the floating diffusion output amplifier. On each falling edge of H1L a new charge packet is dumped onto a floating diffusion and sensed by the output amplifier.



HORIZONTAL REGISTER

Output Structure

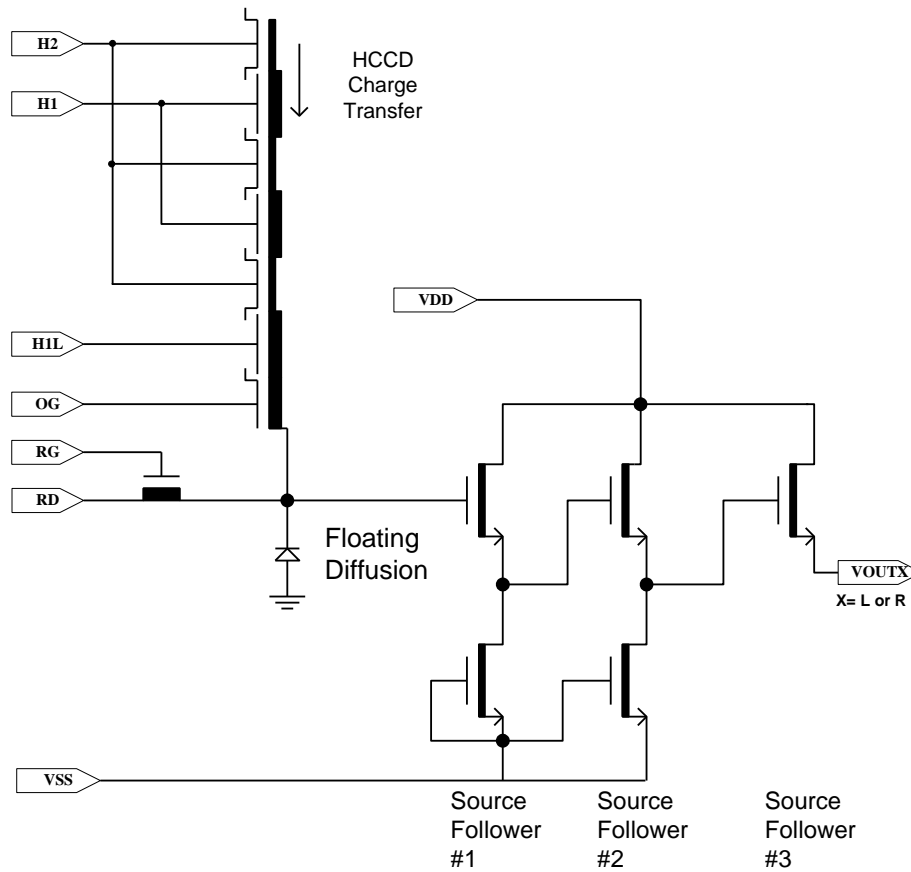


Figure 2: Output Architecture (Left or Right)

The output consists of a floating diffusion capacitance connected to a three-stage source follower. Charge presented to the floating diffusion (FD) is converted into a voltage and is current amplified in order to drive off-chip loads. The resulting voltage change seen at the output is linearly related to the amount of charge placed on the FD. Once the signal has been sampled by the system electronics, the reset gate (RG) is clocked to remove the signal and FD is reset to the potential applied by reset drain (RD). Increased signal at the floating diffusion reduces the voltage seen at the output pin. To activate the output structures, an off-chip current source must be added to the VOUT pins of the device. See Figure 3.



Output Load

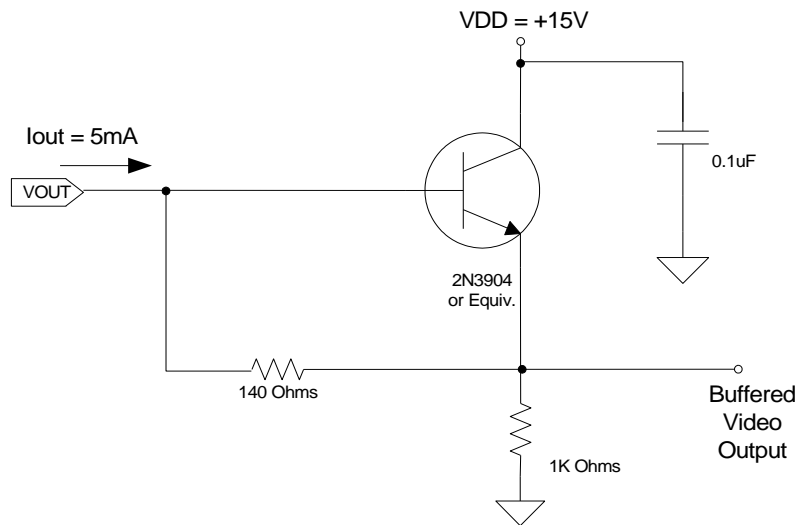


Figure 3: Typical Output Structure Load Diagram

Note: Component values may be revised based on operating conditions and other design considerations.



PHYSICAL DESCRIPTION

Pin Description and Device Orientation

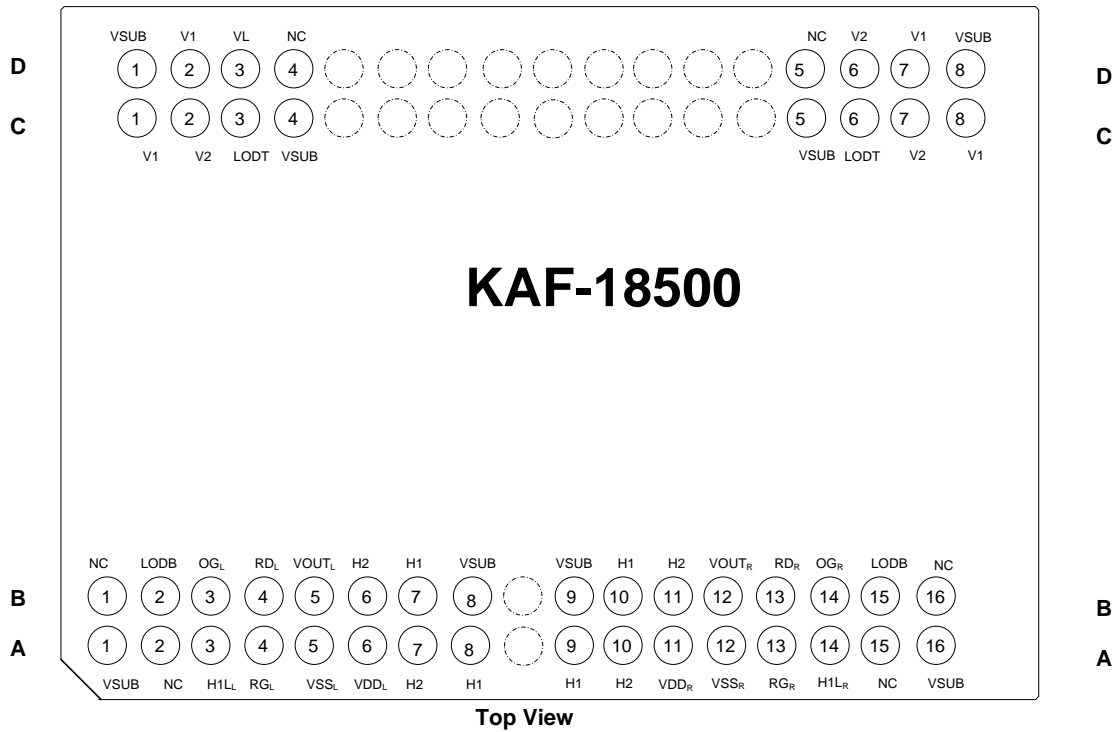


Figure 4: Pinout Diagram - Top View



| PGA Grid Row A | | |
|----------------|------------------|--|
| Pin | Name | Description |
| 1 | VSUB | Substrate |
| 2 | NC | Physical pin with no connection on die |
| 3 | H1L _L | Horizontal Phase 1, last phase, left side |
| 4 | RG _L | Reset Drain, left side |
| 5 | VSS _L | Output Amplifier Return, left side |
| 6 | VDD _L | Output Amplifier Supply, left side |
| 7 | H2 | Horizontal Phase 2 |
| 8 | H1 | Horizontal Phase 1 |
| 9 | H1 | Horizontal Phase 1 |
| 10 | H2 | Horizontal Phase 2 |
| 11 | VDD _R | Output Amplifier Supply, right side |
| 12 | VSS _R | Output Amplifier Return, right side |
| 13 | RG _R | Reset Gate, right side |
| 14 | H1L _R | Horizontal Phase 1, last phase, right side |
| 15 | NC | Physical pin with no connection on die |
| 16 | VSUB | Substrate |

| PGA Grid Row B | | |
|----------------|-------------------|--|
| Pin | Name | Description |
| 1 | N/C | Physical Pin with No Connection on Die |
| 2 | LODB | Lateral Overflow Drain, bottom |
| 3 | OG _L | Output Gate, left side |
| 4 | RD _L | Reset Gate, left side |
| 5 | VOUT _L | Video Output: left side |
| 6 | H2 | Horizontal Phase 2 |
| 7 | H1 | Horizontal Phase 1 |
| 8 | VSUB | Substrate |
| 9 | VSUB | Substrate |
| 10 | H1 | Horizontal Phase 1 |
| 11 | H2 | Horizontal Phase 2 |
| 12 | VOUT _R | Video Output: right side |
| 13 | RD _R | Reset Drain, right side |
| 14 | OG _R | Output Gate, right side |
| 15 | LODB | Lateral Overflow Drain, bottom |
| 16 | N/C | Physical Pin with No Connection on Die |

| PGA Grid Row C | | |
|----------------|------|-----------------------------|
| Pin | Name | Description |
| 1 | V1 | Vertical Phase 1 |
| 2 | V2 | Vertical Phase 2 |
| 3 | LODT | Lateral Overflow Drain, top |
| 4 | VSUB | Substrate |
| 5 | VSUB | Substrate |
| 6 | LODT | Lateral Overflow Drain, top |
| 7 | V2 | Vertical Phase 2 |
| 8 | V1 | Vertical Phase 1 |

| PGA Grid Row D | | |
|----------------|------|--|
| Pin | Name | Description |
| 1 | VSUB | Substrate |
| 2 | V1 | Vertical Phase 1 |
| 3 | V2 | Vertical Phase 2 |
| 4 | N/C | Physical Pin with No Connection on Die |
| 5 | N/C | Physical Pin with No Connection on Die |
| 6 | V2 | Vertical Phase 2 |
| 7 | V1 | Vertical Phase 1 |
| 8 | VSUB | Substrate |



Imaging Performance

TYPICAL OPERATIONAL CONDITIONS

| Description | Condition | Notes |
|--|---|---------------------------|
| Frame Time ($t_{\text{readout}} + t_{\text{int}}$) | Varies, see below | Includes overclock pixels |
| Readout time (t_{readout}) | 527 ms | |
| Integration time (t_{int}) | Varies per test: Bright Field 250 ms, Dark Field 1 sec, Saturation 250 ms, Low light 33 ms | |
| Horizontal clock frequency | 24 MHz | |
| Temperature | 20 – 25 °C | Room temperature |
| Mode | Integrate – readout cycle | |
| Operation | Nominal operating voltages and timing with min. vertical pulse width $t_{\text{vw}} = 11 \mu\text{s}$ | |

SPECIFICATIONS

| Description | Symbol | Min. | Nom. | Max. | Units | Notes | Verification Plan |
|---|---|----------------|------------------------|------|---|-------|--|
| Saturation Signal | Vsat Ne ⁻ _{sat} Q/V | 900 (35000) | 1086 42,000 25.6 | | mV e ⁻ μV/e ⁻ | 1, 19 | die ¹⁷ design ¹⁸ design ¹⁸ |
| Peak Quantum Efficiency | Rr Rg Rb | | 30 45 40 | | % % % | | design ¹⁸ design ¹⁸ design ¹⁸ |
| High Level Photoresponse Non-Linearity | Le_High | | 2 | 10 | % | 2 | die ¹⁷ |
| Low Level Photoresponse Non-Linearity | Le_Low | | 2 | 10 | % | 2 | die ¹⁷ |
| Photo Response Non-Uniformity each color plane | PRNU | | 4.5 | 25 | %p-p | 3 | die ¹⁷ |
| Integration Dark Signal | Vdark,int | | 4 | 10 | mV/s | 4,16 | die ¹⁷ |
| Readout Dark Signal | Vdark,read | | 12 | 20 | mV/s | 15,16 | die ¹⁷ |
| Dark Signal Non-Uniformity | DSNU | | 0.5 | 4 | mV p-p | 5 | die ¹⁷ |
| Dark Signal Doubling Temperature | ΔT | | 5.3 | | °C | | design ¹⁸ |
| Read Noise | N _R | | 15.7 | | e ⁻ rms | | design ¹⁸ |
| Total Noise | N | | 18.9 | | e ⁻ rms | 6 | design ¹⁸ |
| Linear Dynamic Range | DR | | 68.1 | | dB | 7 | design ¹⁸ |
| Red-Green Hue Shift Blue-Green Hue Shift | RGHueUnif BGHueUnif | | 1.8 | 12 | % | 8 | die ¹⁷ |
| Horizontal Charge Transfer Efficiency | HCTE | 0.999995 | 0.999995 | | | 9 | die ¹⁷ |
| Vertical Charge Transfer Efficiency | VCTE | 0.999999 | 0.999998 | | | | die ¹⁷ |
| Blooming Protection | Xab | | 5600 | | x Vsat | 10 | design ¹⁸ |
| DC Offset, output amplifier | Vodc | 6.0 | 8 | 9.5 | V | 11 | die ¹⁷ |
| Output Amplifier Bandwidth | f _{-3dB} | | 232 | | MHz | 12 | design ¹⁸ |
| Output Impedance, Amplifier | R _{OUT} | 100 | 137 | 300 | Ohms | | die ¹⁷ |
| Hclk Feedthru | V _{hft} | | 3.7 | 20 | mV | 13 | die ¹⁷ |
| Reset Feedthru | V _{rf} | | 0.5 | | V | 14 | design ¹⁸ |



Notes:

1. Increasing output load currents to improve bandwidth will decrease the conversion factor (Q/V).
2. Worst-case deviation (from 10 mV to $V_{sat \text{ min}}$), relative to a linear fit applied between 0 and 85% of $V_{sat \text{ min}}$.
3. Difference between the maximum and minimum average signal levels of 148 x 148 blocks within the sensor on a per color basis as a % of average signal level.
4. T = 60 °C. Average non-illuminated signal with respect to over-clocked vertical register signal.
5. T = 60 °C. Absolute difference between the maximum and minimum average signal levels of 148 x 148 blocks within the sensor.
6. rms deviation of a multi-sampled pixel measured in the dark including amplifier and system noise sources.
7. $20\log(0.95 \cdot V_{sat}/VN)$. Specified at T = 60 °C.
8. Gradual variations in hue (red with respect to green pixels and blue with respect to green pixels) in regions of interest (148 x 148 blocks) within the sensor.
9. Measured per transfer at $V_{sat \text{ min}}$. Typically, no degradation in CTE is observed up to 24 MHz.
10. X_{ab} is the number of times above the V_{sat} illumination level that the sensor will bloom by spot size doubling. The spot size is 10% of the imager height. X_{ab} is measured at 4 ms.
11. Video level offset with respect to ground.
12. Last stage only. Assumes 5 pF off-chip load.
13. Amount of artificial signal due to H1 coupling.
14. Amplitude of feedthrough pulse in VOUT due to RG coupling.
15. T = 60 °C. Average non-illuminated signal collected due to the read out time.
16. Total dark signal = $(V_{\text{dark,int}} \times t_{\text{int}}) + (V_{\text{dark,read}} \times t_{\text{readout}})$.
17. A parameter that is measured on every sensor during production testing.
18. A parameter that is quantified during the design verification activity.
19. Specified at T = 60 °C.



Typical Performance Curves

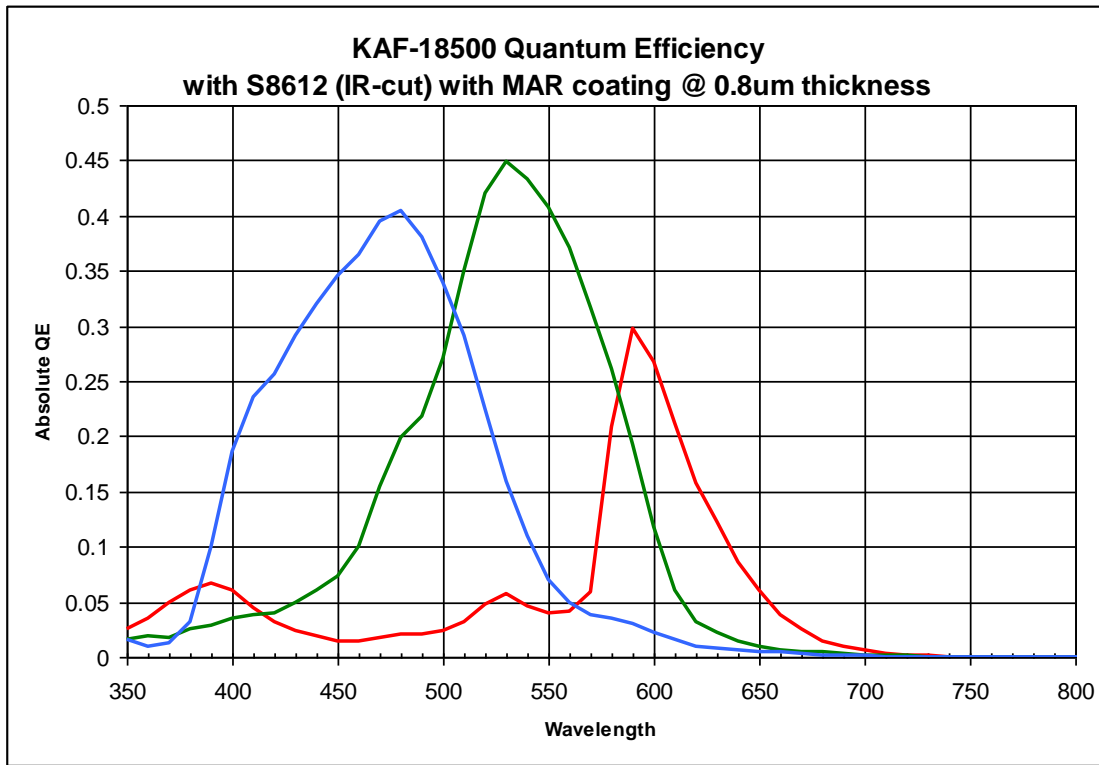


Figure 5: Typical Quantum Efficiency

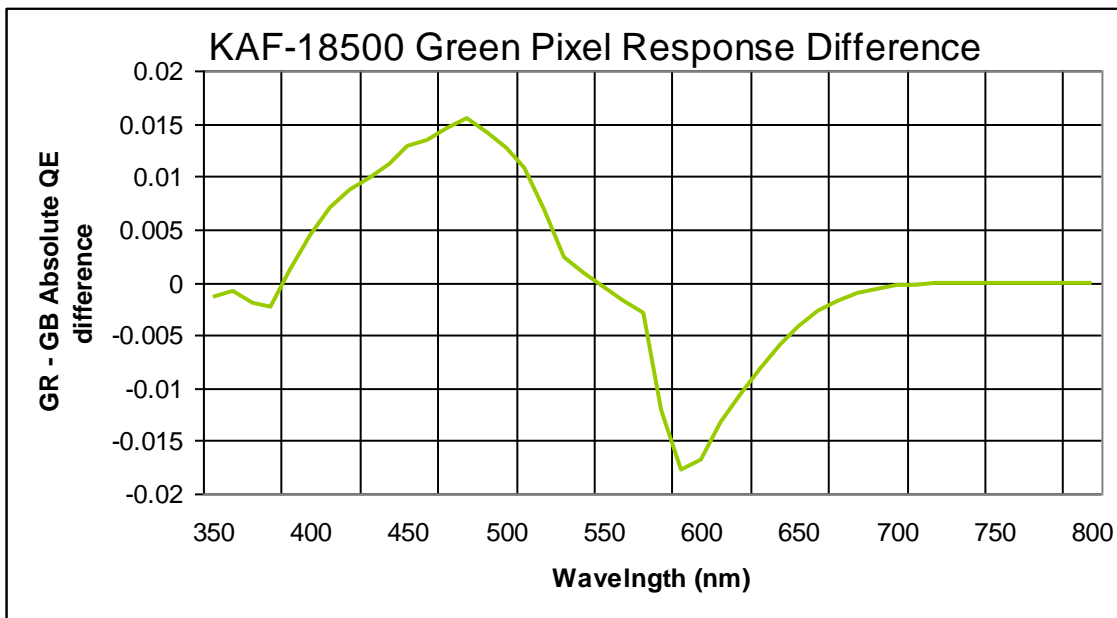


Figure 6: Typical GR-GB QE Difference

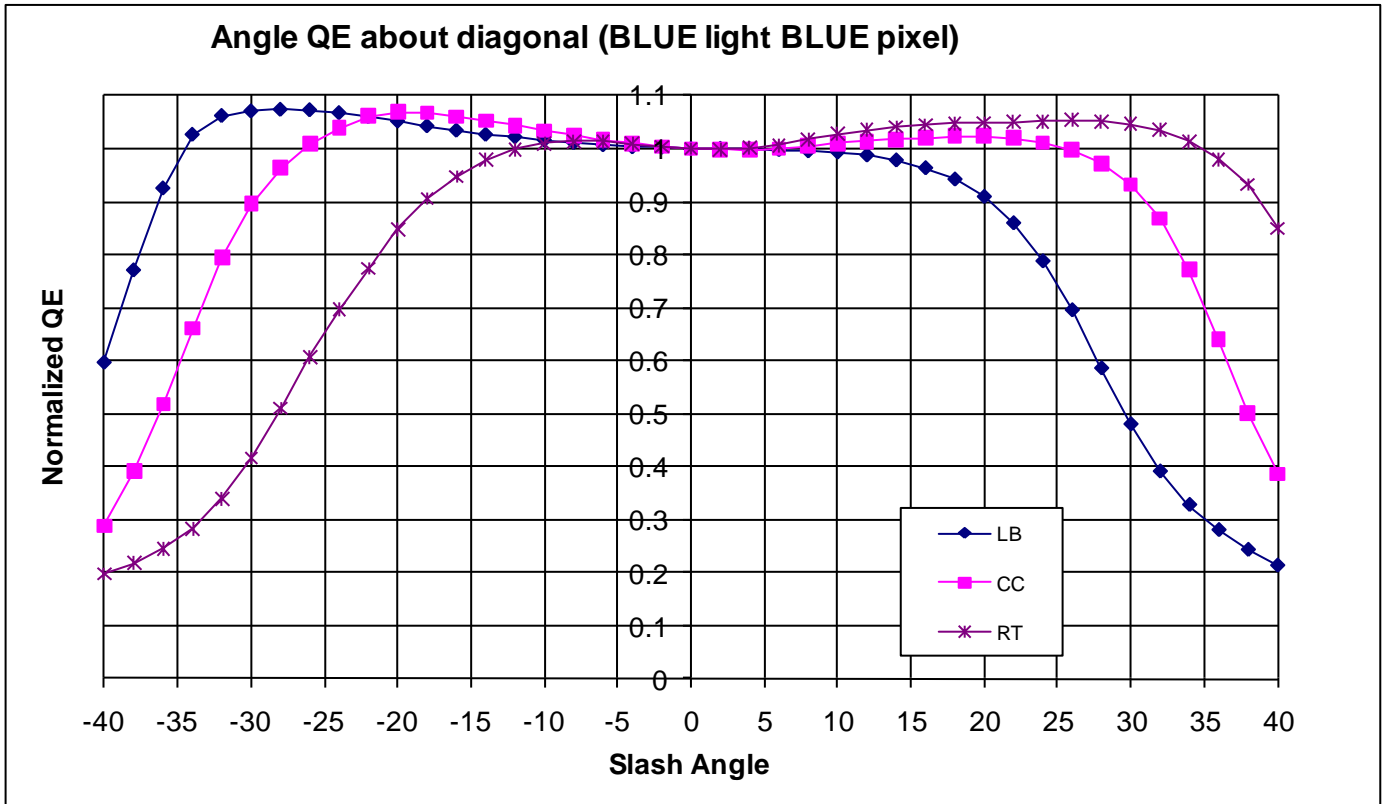


Figure 7: Typical Normalized Angle QE

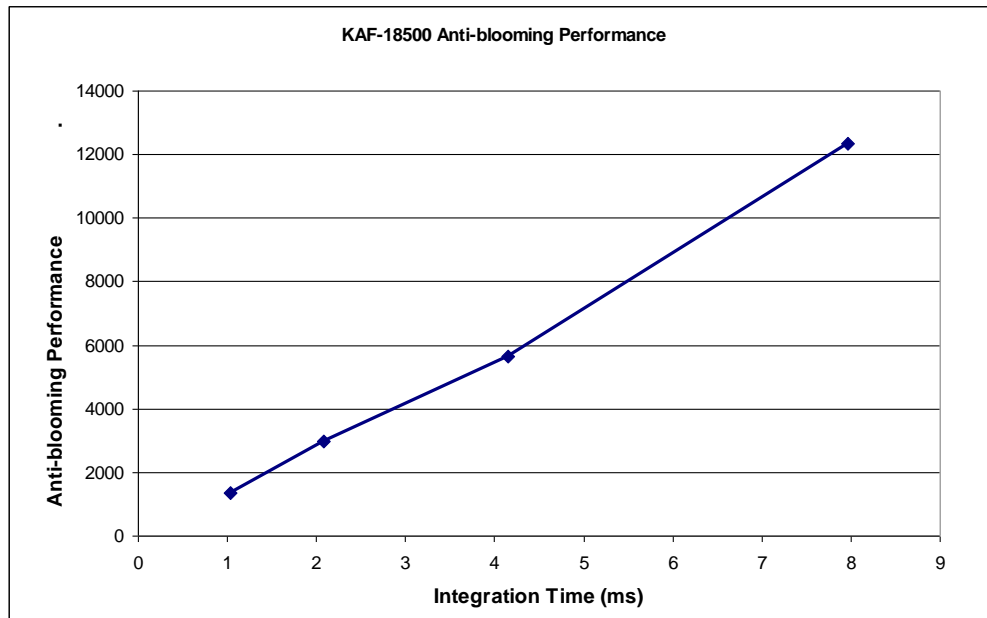


Figure 8: Typical Anti Blooming Performance



Defect Definitions

OPERATING CONDITIONS

All defect tests performed at:

| Description | Condition | Notes |
|--------------------------------|---|------------------|
| Integration time (t_{int}) | Varies per test: Bright Field 250 ms, Dark Field 1 sec, Saturation 250 ms, Low light 33 ms | |
| Horizontal clock frequency | 24 MHz | |
| Temperature | 20 – 25 °C | Room temperature |

SPECIFICATIONS

| Classification | Points | Clusters, small and large | Clusters, large | Columns | Includes dead columns |
|----------------|---------|---------------------------|-----------------|---------|-----------------------|
| Standard Grade | ≤ 4,400 | ≤ 50 | ≤ 5 | ≤ 15 | yes |

Point Defects A pixel that deviates by more than 9 mV above neighboring pixels under non-illuminated conditions.

-- OR --

A pixel that deviates by more than 7% above or 11% below neighboring pixels under illuminated conditions.

Cluster Defect Small clusters: A grouping of adjacent point defects that can number in size from 2 to 10 pixels. Large clusters: A grouping of more than 10 pixels but not larger than 20 adjacent point defects. A single large cluster is not to exceed 5 adjacent pixels within the same color plane.

Cluster Separation Cluster defects are separated by no less than 4 good pixels in any direction .

Column Defect A grouping of more than 10 point defects along a single column.

-- OR --

A column that deviates by more than 0.9 mV above or below neighboring columns under non-illuminated conditions.

-- OR --

A column that deviates by more than 1.5% above or below neighboring columns under illuminated conditions.

Column and cluster defects are separated by at least 4 good columns in the x direction. No multiple column defects (double or more) will be permitted.

Dead Columns A column that deviates by more than 50% below neighboring columns under illuminated conditions

Saturated Columns A column that deviates by more than 100 mV above neighboring columns under non-illuminated conditions. No saturated columns are allowed.



Operation

ABSOLUTE MAXIMUM RATINGS

| Description | Symbol | Minimum | Maximum | Units | Notes |
|-----------------------|--------|---------|---------|-------|-------|
| Diode Pin Voltages | Vdiode | -0.5 | +17.5 | V | 1,2 |
| Gate Pin Voltages | Vgate1 | -13.5 | +13.5 | V | 1,3 |
| Gate - Gate Voltages | V1-2 | -13.5 | +13.5 | V | 4,5 |
| Output Bias Current | Iout | | -30 | mA | 6 |
| LOD Diode Voltage | VLODT | -0.5 | +13.0 | V | 7 |
| Operating Temperature | TOP | 0 | 60 | °C | 8 |

Notes:

1. Referenced to pin SUB.
2. Includes pins: RD, VDD, VSS, VOUT.
3. Includes pins: V1, V2, H1, H1L, H2, RG, OG.
4. Voltage difference between overlapping gates. Includes: V1 to V2; H1, H1L to H2; H1L to OG; V1 to H2. These inputs contain an ESD protection circuit. Exceeding the maximum voltages will cause an uncontrolled current to flow in these circuits and may damage the input pin.
5. Voltage difference between non-overlapping gates. Includes: V1 to H1, H1L; V2, OG to H2. These inputs contain an ESD protection circuit. Exceeding the maximum voltages will cause an uncontrolled current to flow in these circuits and may damage the input pin.
6. Avoid shorting output pins to ground or any low impedance source during operation. Amplifier bandwidth increases at higher currents and lower load capacitance at the expense of reduced gain (sensitivity). Operation at the maximum values will reduce Mean Time to Failure (MTTF).
7. V1, H1, V2, H2, H1L, OG, and RD are tied to 0 V.
8. Noise performance will degrade at higher temperatures.
9. Absolute maximum rating is defined as a level or condition that should not be exceeded at any time per the description. If the level or condition is exceeded, the device will be degraded and may be damaged.

POWER-UP SEQUENCE

The sequence chosen to perform an initial power-up is not critical for device reliability. A coordinated sequence may minimize noise and the following sequence is recommended:

- a. Connect the ground pins (SUB).
- b. Supply the appropriate biases and clocks to the remaining pins.



DC BIAS OPERATING CONDITIONS

| Description | Symbol | Minimum | Nominal | Maximum | Units | Maximum DC Current (mA) | Notes |
|-------------------------|--------|---------|---------|---------|-------|-------------------------|-------|
| Reset Drain | RD | 11.3 | 11.5 | 11.7 | V | IRD = 0.01 | |
| Output Amplifier Return | VSS | 0.5 | 0.7 | 1.0 | V | ISS = 3.0 | |
| Output Amplifier Supply | VDD | 14.5 | 15.0 | 15.5 | V | IOUT + ISS | |
| Substrate | SUB | | 0 | | V | 0.01 | |
| Output Gate | OG | -2.2 | -2.0 | -1.8 | V | 0.01 | |
| Lateral Drain | LOD | 9.8 | 10.0 | 10.2 | V | 0.01 | |
| Video Output Current | IOUT | | -5 | -10 | mA | | 1 |

Notes:

1. An output load sink must be applied to VOUT to activate output amplifier - see Figure 3.

AC OPERATING CONDITIONS

Clock Levels

| Description | Symbol | Level | Minimum | Nominal | Maximum | Units | Effective Capacitance | Notes |
|-----------------------|----------------|-----------|---------|---------|---------|-------|-----------------------|-------|
| V1 Low Level | V1L | Low | -9.2 | -9.0 | -8.8 | V | 245 nF | 1,2 |
| V1 High Level | V1H | High | 2.3 | 2.5 | 2.7 | | | |
| V2 Low Level | V2L | Low | -9.2 | -9.0 | -8.8 | V | 303 nF | 1,2 |
| V2 High Level | V2H | High | 2.3 | 2.5 | 2.7 | | | |
| H1, H2 (amplitude) | H1amp H2amp | Amplitude | 6.5 | 6.75 | 7.0 | V | See below | |
| H1 Low Level | H1Low | Low | -4.7 | -4.5 | -4.3 | V | 460 pF | 1 |
| H2 Low Level | H2Low | Low | -5.2 | -5.0 | -4.8 | V | 302 pF | 1 |
| H1L Low Level | H1Llow | Low | -6.7 | -6.5 | -6.3 | V | 15 pF | 1 |
| H1L High Level | H1Lhigh | High | 1.3 | 1.5 | 1.7 | | | |
| RG Low Level | RGL | Low | 0.3 | 0.5 | 0.7 | V | 21 pF | 1 |
| RG High Level | RGH | High | 7.8 | 8.0 | 8.2 | | | |

Notes:

1. All pins draw less than 10 μ A DC current. Capacitance values relative to SUB (substrate).
2. Clock capacitance is the effective capacitance extrapolated from the rise and fall time measured while operating the sensor.



Timing

REQUIREMENTS AND CHARACTERISTICS

| Description | Symbol | Minimum | Nominal | Maximum | Units | Notes |
|------------------------------|--------------------|---------|---------|---------|---------|-------|
| H1, H2 Clock Frequency | f_H | | | 24 | MHz | 1, 2 |
| V1, V2 Clock Frequency | f_V | | | 45.5 | kHz | 1, 2 |
| H1, H2 Rise, Fall Times | t_{H1r}, t_{H1f} | 5 | | 10 | % | 3, 7 |
| V1, V2 Rise, Fall Times | t_{V1r}, t_{V1f} | 5 | | 10 | % | 3 |
| V1 - V2 Cross-over | V_{VCR} | 1 | | | V | |
| H1 - H2 Cross-over | V_{HCR} | -3.0 | -1.5 | 0 | V | |
| H1L Rise – H2 Fall Crossover | V_{H1LCR} | -2.0 | | 1.0 | V | 9 |
| H1, H2 Setup Time | t_{HS} | 1 | 5 | | μ s | |
| RG Clock Pulse Width | t_{RGW} | 5 | | | ns | 4 |
| RG Rise, Fall Times | t_{RGr}, t_{RGf} | 5 | | 10 | % | 3 |
| V1, V2 Clock Pulse Width | t_{VW} | 11 | | | μ s | 2, 6 |
| Flush clock off time | t_{off} | 4 | | | μ s | 2, 6 |
| Pixel Period (1 Count) | t_e | 42 | | | ns | 2 |
| H1L – VOUT Delay | t_{HV} | | 5 | | ns | |
| RG - VOUT Delay | t_{RV} | | 5 | | ns | |
| Readout Time | $t_{readout}$ | 505 | | | ms | 6, 8 |
| Integration Time | t_{int} | | - | | | 5, 6 |
| Line Time | t_{line} | 140 | | | μ s | 6 |
| Fast Flush Time | t_{flush} | 88 | | | ms | |

Notes:

1. 50% duty cycle values.
2. CTE will degrade above the nominal frequency.
3. Relative to the pulse width (based on 50% of high/low levels).
4. RG should be clocked continuously.
5. Integration time is user specified.
6. Longer times will degrade noise performance.
7. The maximum specification or 10 nsec whichever is greater based on the frequency of the horizontal clocks.
8. $t_{readout} = t_{line} * 3610$ lines.
9. The charge capacity near the output could be degraded if the voltage at the clock cross over point is outside this range.



EDGE ALIGNMENT

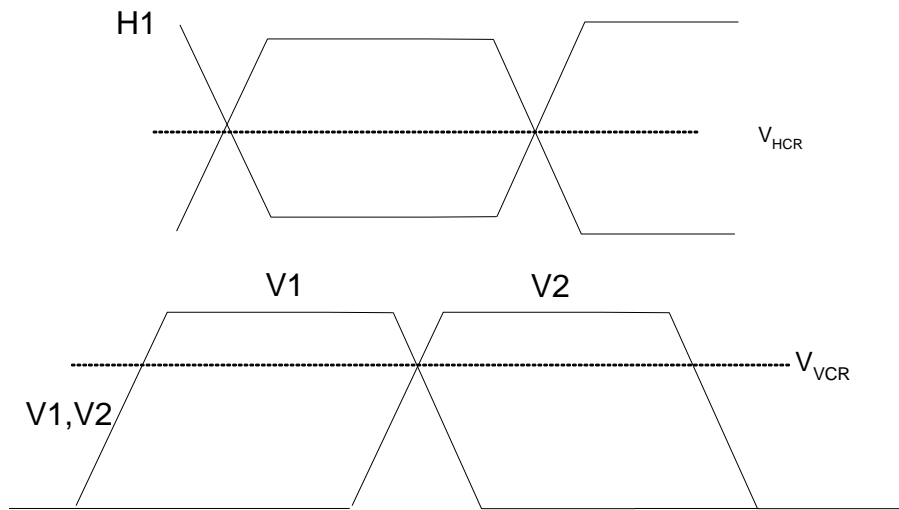


Figure 9: Timing Edge Alignment



FRAME TIMING

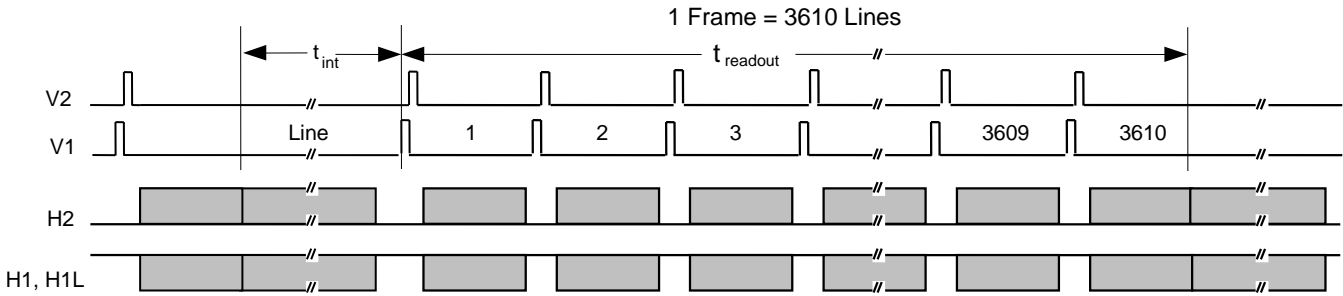


Figure 10: Frame Timing

Frame Timing Detail

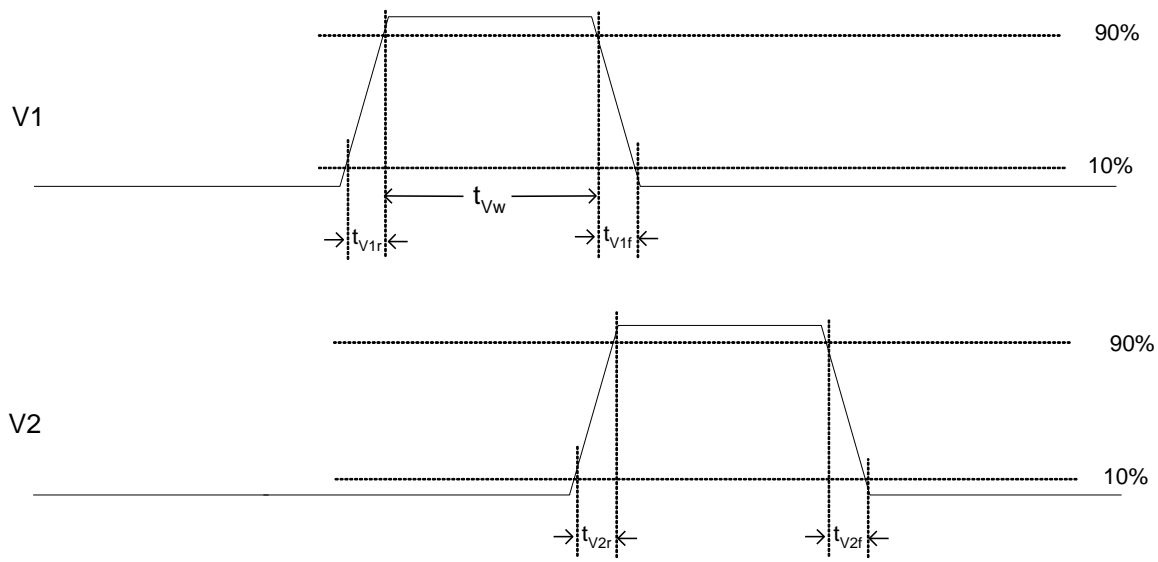


Figure 11: Frame Timing Detail



LINE TIMING (EACH OUTPUT)

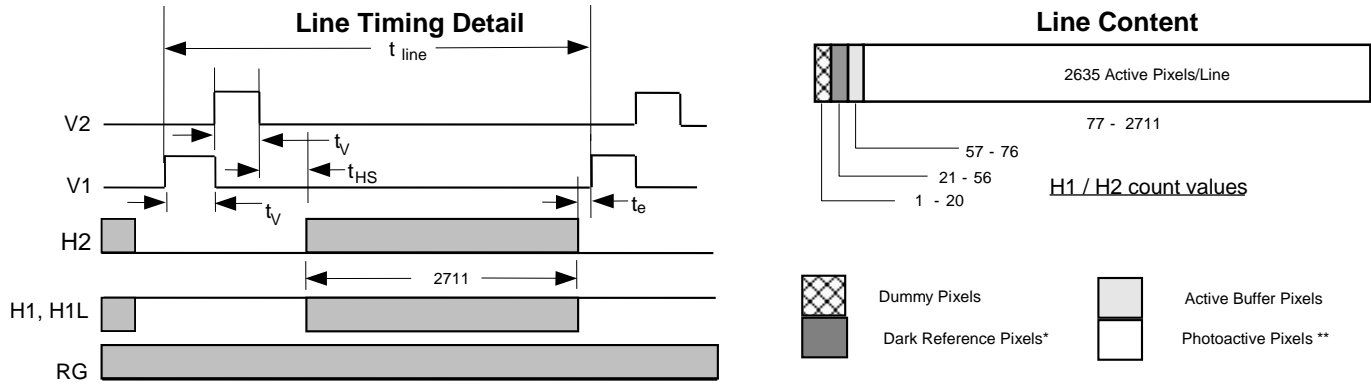


Figure 12: Line Timing



PIXEL TIMING

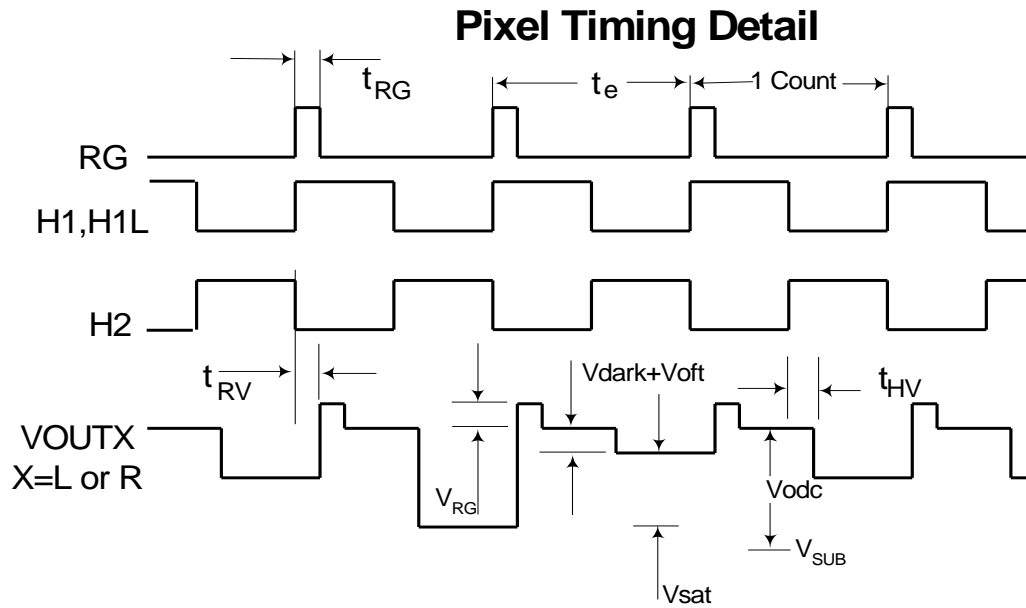


Figure 13: Pixel Timing



Pixel Timing Detail

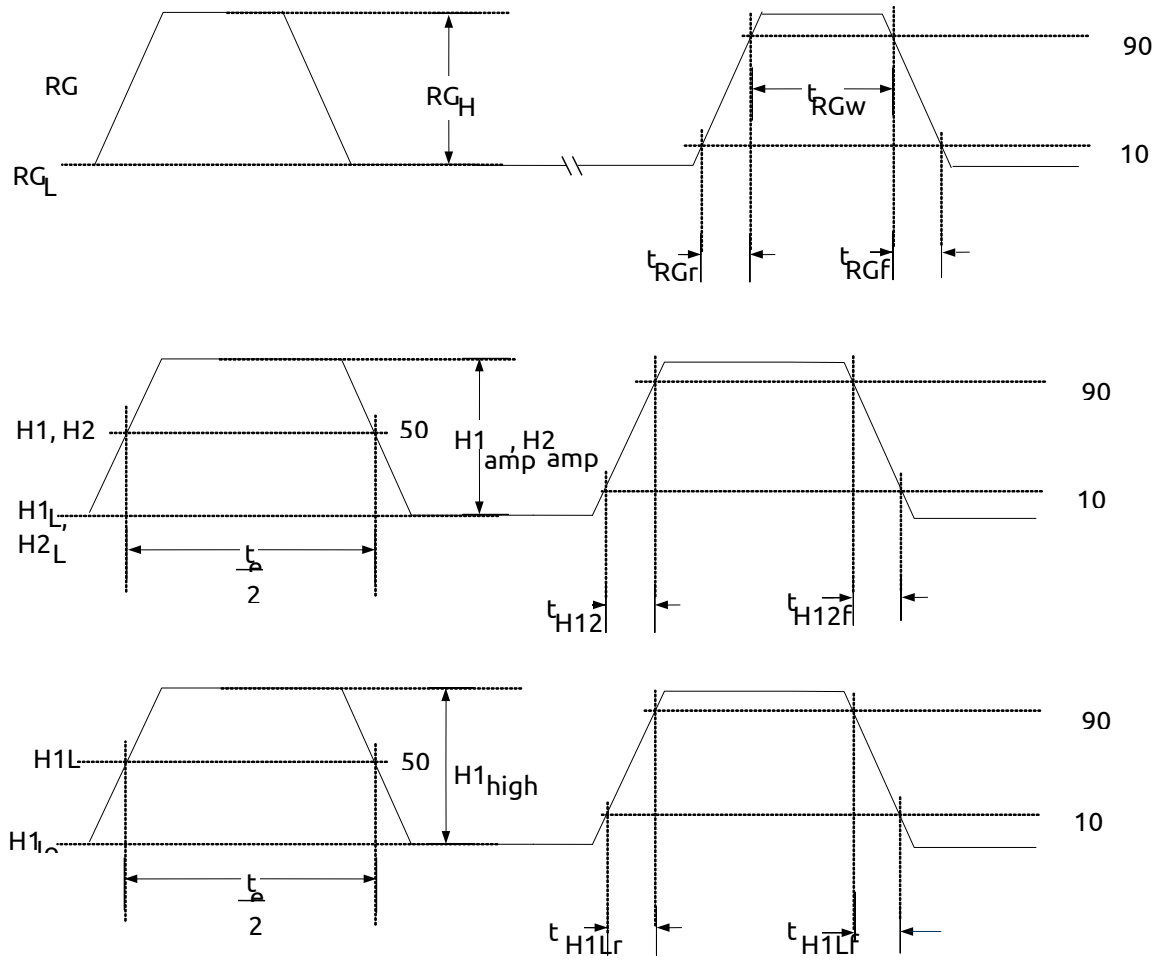


Figure 14: Pixel Timing Detail



MODE OF OPERATION

POWER-UP FLUSH CYCLE

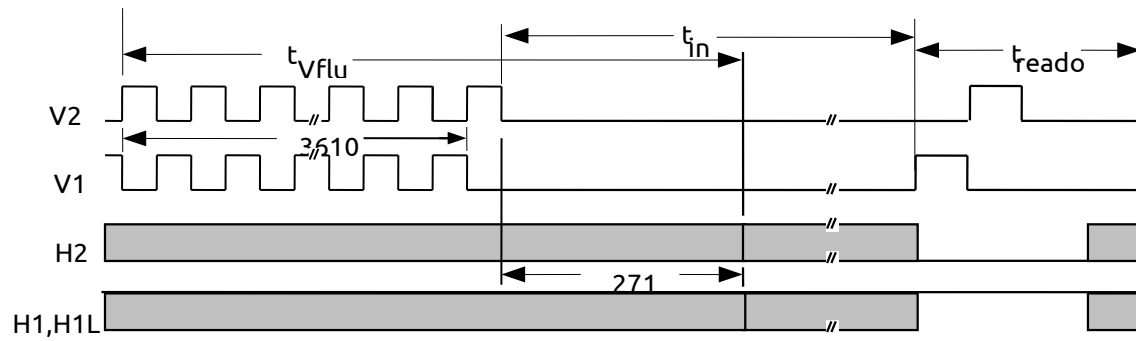


Figure 15: Power-up Flush Cycle



Storage and Handling

STORAGE CONDITIONS

| Description | Symbol | Minimum | Maximum | Units | Notes |
|---------------------|-----------------|---------|---------|-------|-------|
| Storage Temperature | T _{ST} | -20 | 70 | °C | 1 |
| Humidity | RH | 5 | 70 | % | 2 |

Notes:

1. Long-term storage toward the maximum temperature will accelerate color.
2. Excessive humidity will degrade MTF.

ESD

1. This device contains limited protection against Electrostatic Discharge (ESD). ESD events may cause irreparable damage to a CCD image sensor either immediately or well after the ESD event occurred. Failure to protect the sensor from electrostatic discharge may affect device performance and reliability.
2. Devices should be handled in accordance with strict ESD procedures for Class 0 (<250 V per JESD22 Human Body Model test), or Class A (<200 V JESD22 Machine Model test) devices. Devices are shipped in static-safe containers and should only be handled at static-safe workstations.
3. See Application Note *Image Sensor Handling Best Practices* for proper handling and grounding procedures. This application note also contains workplace recommendations to minimize electrostatic discharge.
4. Store devices in containers made of electro-conductive materials.

COVER GLASS CARE AND CLEANLINESS

1. The cover glass is highly susceptible to particles and other contamination. Perform all assembly operations in a clean environment.
2. Touching the cover glass must be avoided.
3. Improper cleaning of the cover glass may damage these devices. Refer to Application Note *Image Sensor Handling Best Practices*.

ENVIRONMENTAL EXPOSURE

1. Extremely bright light can potentially harm CCD image sensors. Do not expose to strong sunlight for long periods of time, as the color filters and/or microlenses may become discolored. In addition, long time exposures to a static high contrast scene should be avoided. Localized changes in response may occur from color filter/microlens aging. For Interline devices, refer to Application Note *Using Interline CCD Image Sensors in High Intensity Visible lighting Conditions*.
2. Exposure to temperatures exceeding maximum specified levels should be avoided for storage and operation, as device performance and reliability may be affected.
3. Avoid sudden temperature changes.
4. Exposure to excessive humidity may affect device characteristics and may alter device performance and reliability, and therefore should be avoided.
5. Avoid storage of the product in the presence of dust or corrosive agents or gases, as deterioration of lead solderability may occur. It is advised that the solderability of the device leads be assessed after an extended period of storage, over one year.

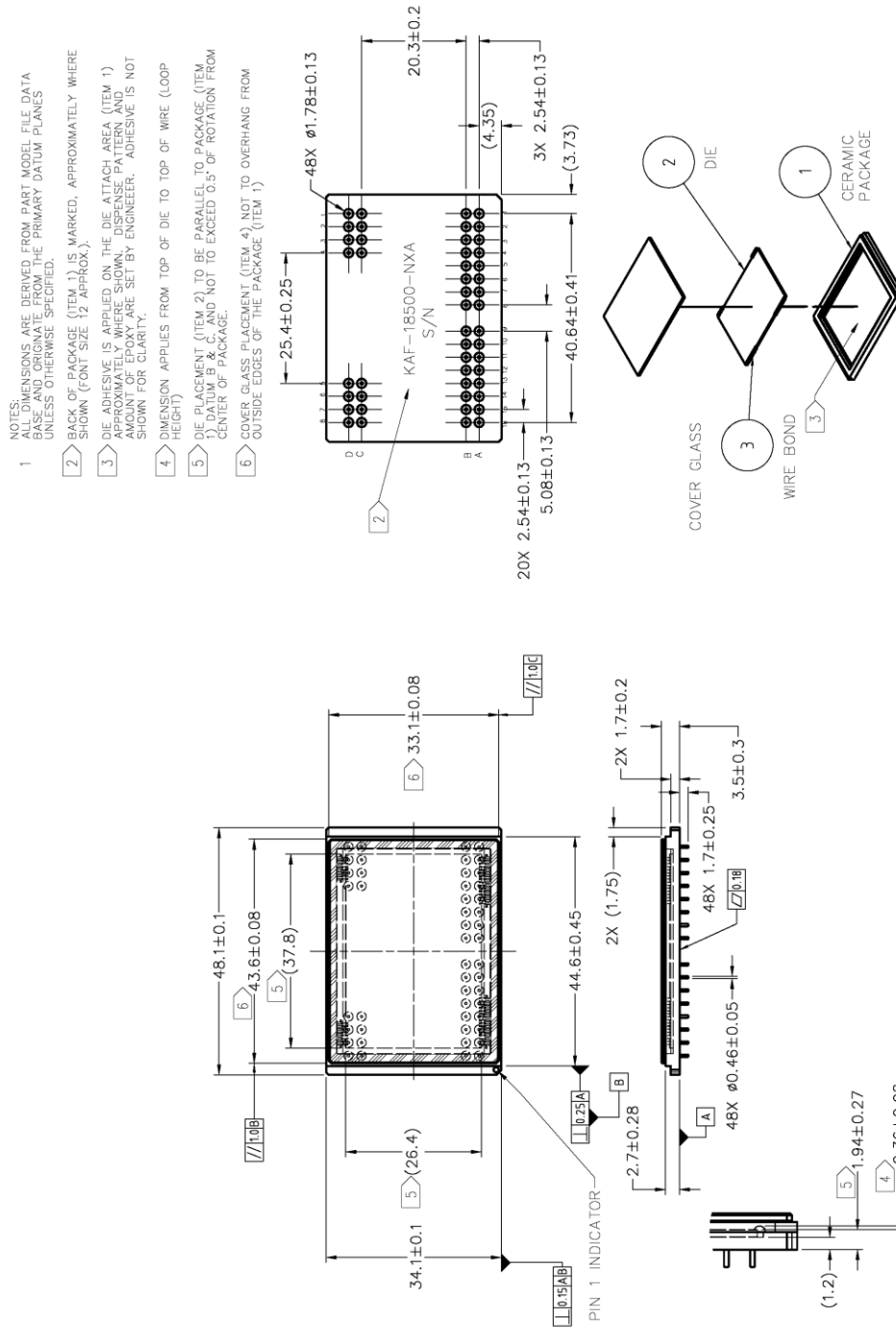
SOLDERING RECOMMENDATIONS

1. The soldering iron tip temperature is not to exceed 370 °C. Higher temperatures may alter device performance and reliability.
2. Flow soldering method is not recommended. Solder dipping can cause damage to the glass and harm the imaging capability of the device. Recommended method is by partial heating using a grounded 30 W soldering iron. Heat each pin for less than 2 seconds duration.



Mechanical Information

COMPLETED ASSEMBLY





COVER GLASS SPECIFICATION

MAR Coated-IR Absorbing Cover Glass

1. Dust/Scratch/Digs/Defects: 20 micron max
2. Substrate material: Schott S8612 whose performance is as published and specifications controlled by Schott, North America. The cover glass supplied for this device is as shown in Figure 16. Data supplied in the graph below is a typical transmission of the AR coated material at 0.8 mm thickness.

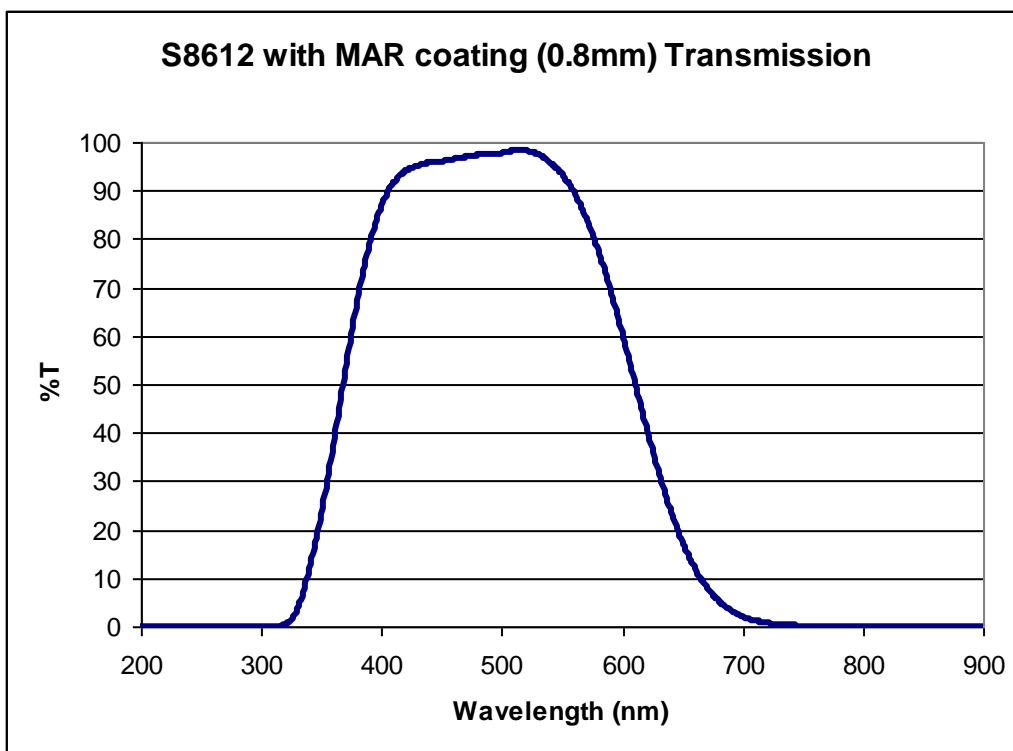


Figure 17: Cover Glass Substrate Transmission

3. Multilayer anti-reflective coating on two sides: Two-sided reflectance:

| Wavelength | Transmission |
|--------------|--------------|
| 420 – 450 nm | < 2 % |
| 450 – 630 nm | < 1 % |
| 630 – 680 nm | < 2 % |



Quality Assurance and Reliability

QUALITY AND RELIABILITY

All image sensors conform to the specifications stated in this document. This is accomplished through a combination of statistical process control and visual inspection and electrical testing at key points of the manufacturing process, using industry standard methods. Information concerning the quality assurance and reliability testing procedures and results are available from ON Semiconductor upon request. For further information refer to Application Note *Quality and Reliability*.

REPLACEMENT

All devices are warranted against failure in accordance with the *Terms of Sale*. Devices that fail due to mechanical and electrical damage caused by the customer will not be replaced.

LIABILITY OF THE SUPPLIER

A reject is defined as an image sensor that does not meet all of the specifications in this document upon receipt by the customer. Product liability is limited to the cost of the defective item, as defined in the *Terms of Sale*.

LIABILITY OF THE CUSTOMER

Damage from mishandling (scratches or breakage), electrostatic discharge (ESD), or other electrical misuse of the device beyond the stated operating or storage limits, which occurred after receipt of the sensor by the customer, shall be the responsibility of the customer.

TEST DATA RETENTION

Image sensors shall have an identifying number traceable to a test data file. Test data shall be kept for a period of 2 years after date of delivery.

MECHANICAL

The device assembly drawing is provided as a reference.

ON Semiconductor reserves the right to change any information contained herein without notice. All information furnished by ON Semiconductor is believed to be accurate.

Life Support Applications Policy

ON Semiconductor image sensors are not authorized for and should not be used within Life Support Systems without the specific written consent of ON Semiconductor.




Revision Changes

MTD/PS-1412

| Revision Number | Description of Changes |
|-----------------|--|
| 1.0 | <ul style="list-style-type: none"> Initial Release. |

PS-0074

| Revision Number | Description of Changes |
|-----------------|---|
| 1.0 | <ul style="list-style-type: none"> Initial release with new document number, updated branding and document template. Updated <i>Storage and Handling</i> and <i>Quality Assurance and Reliability</i> sections. |
| 1.1 | <ul style="list-style-type: none"> Updated branding |

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